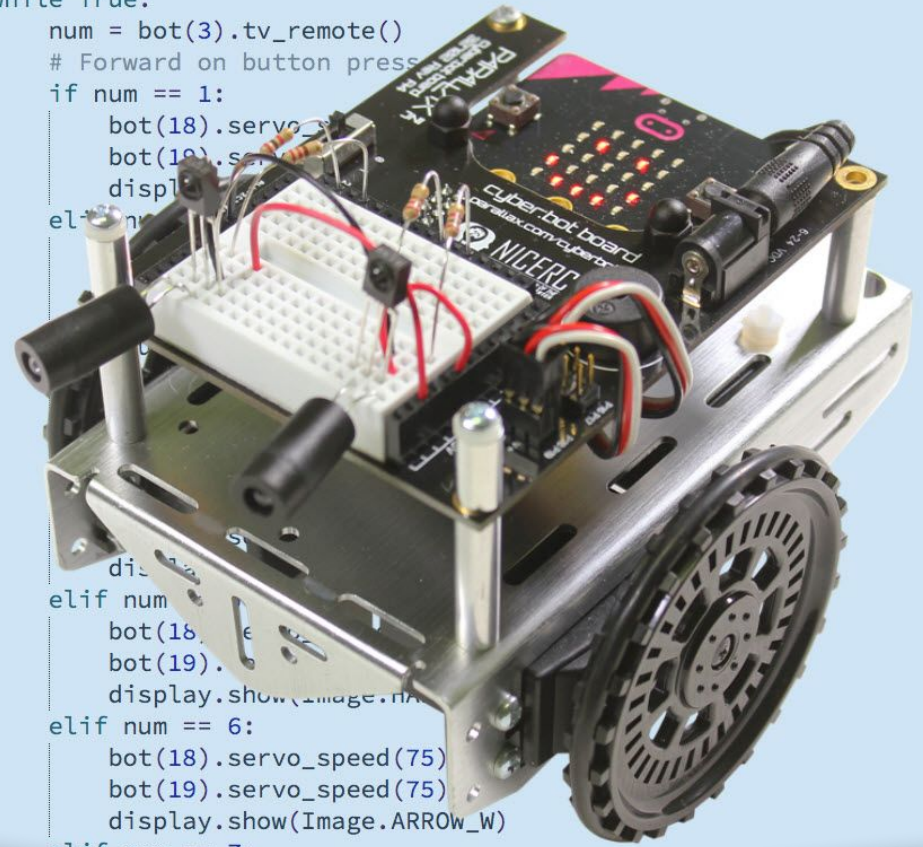
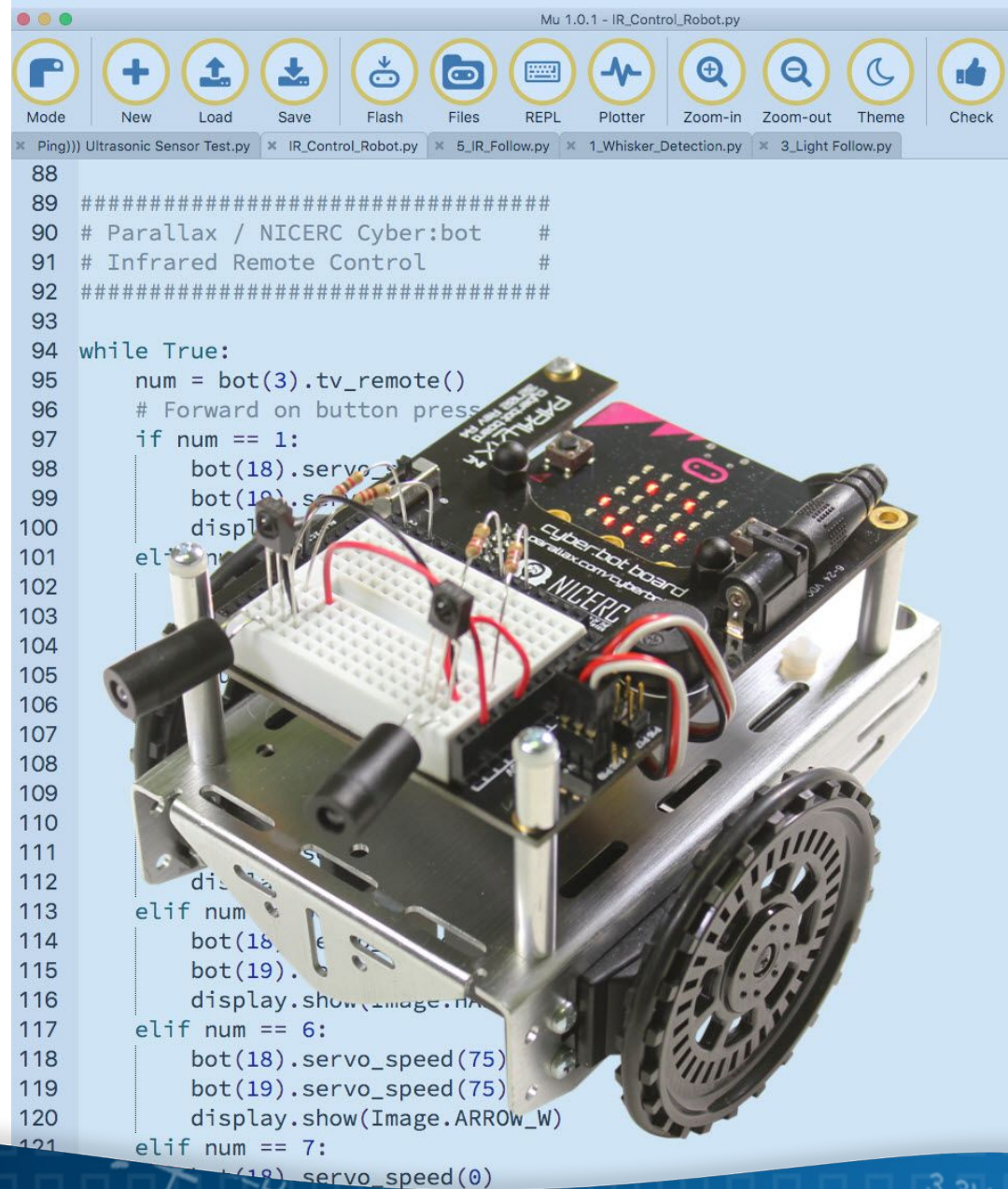


# cyber:bot for micro:bit Webinar

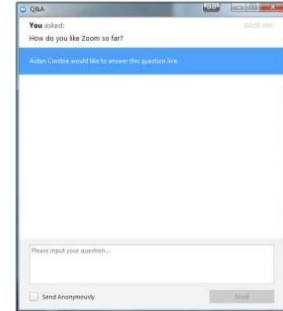
January 24, 2019





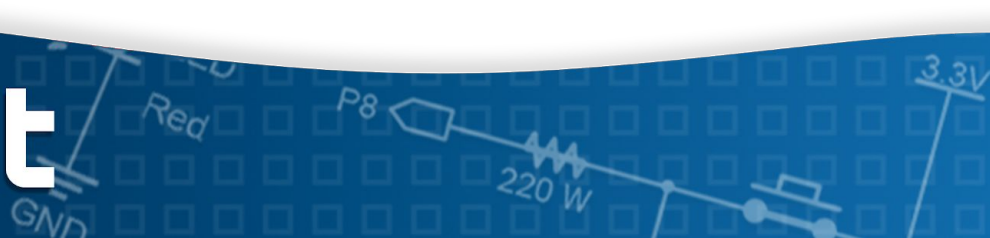
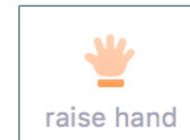
## Q&A

Have a question you'd like us to answer? Use the Q&A functionality in Zoom, and we will do our best to answer them all. Feel free to leave comments in Chat, though we may not see questions left there.



## Raise Hand

If you'd like to speak during the webinar, click the "Raise Hand" button and we will answer you.



# Meet Your Hosts



**Ken Gracey**  
**CEO**  
**Parallax**

kgracey@parallax.com



**Dr. Chuck Gardner**  
**Director of Curriculum**  
**NICERC**

chuck.gardner@cyber.org

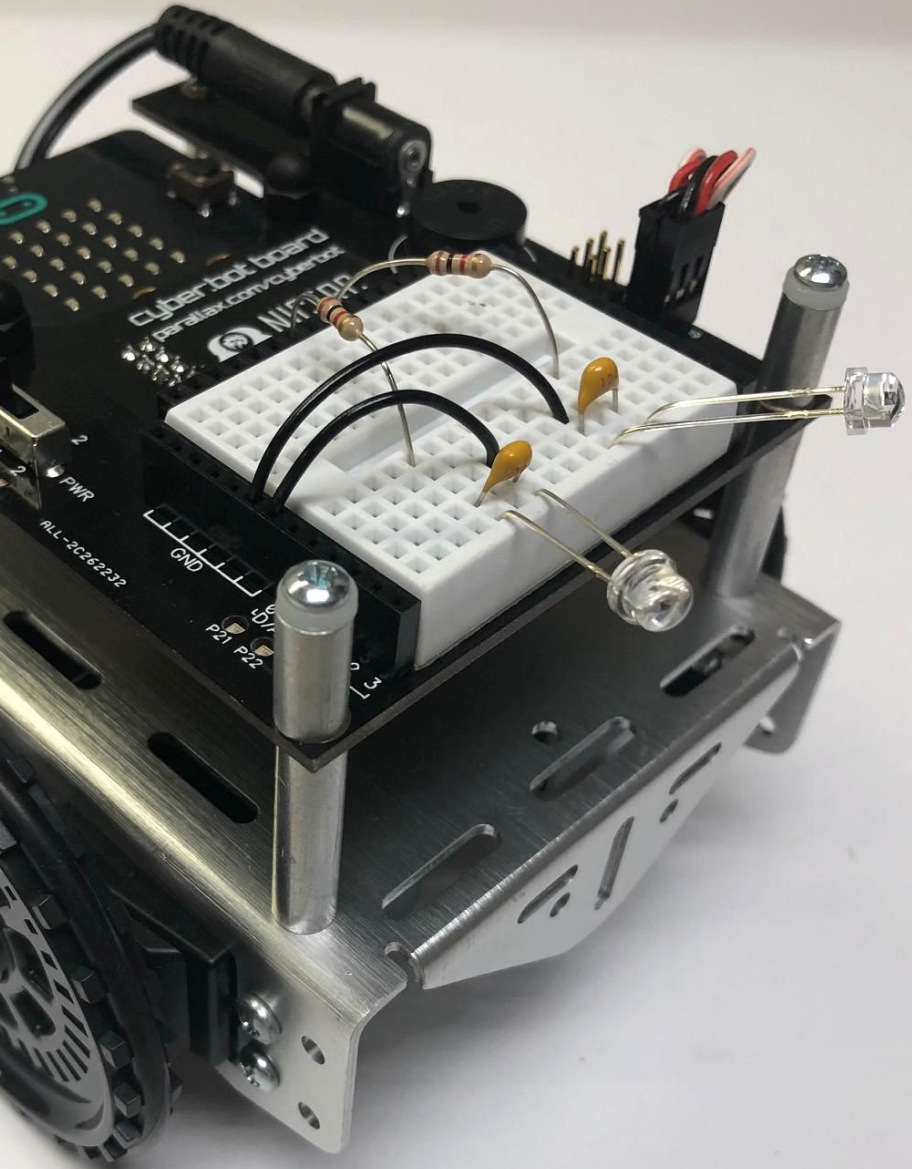


**Tommy Gober**  
**Curriculum Development**  
**Specialist**  
**NICERC**

tommy.gober@cyber.org



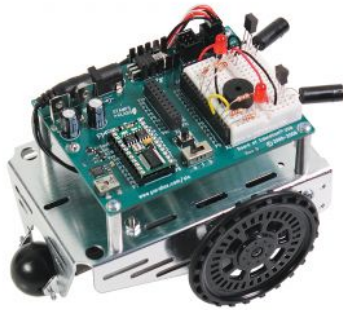




# cyber:bot Webinar Agenda

- Introductions and team (*5 mins*)
- Cyber:bot goals (*2 mins*)
- Micro:bit (*2 mins*)
- Python (*5 mins*)
- `parallax.py` code library (*5 mins*)
- Cyber:bot robot hardware (*10 mins*)
- Curriculum (*10 mins*)
- Demonstrations/code (*15 minutes*)
- Price and availability (*5 mins*)
- Comments and questions (*any*)

# Parallax Small Robots

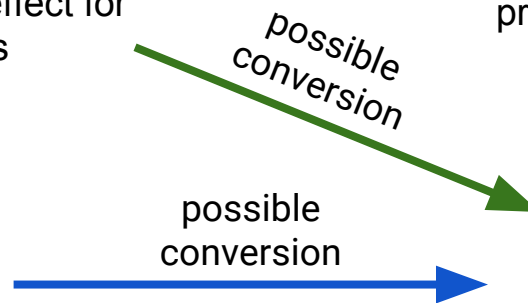


## Boe-Bot with BASIC Stamp

- Program in PBASIC (text)
- Easy language with very direct code/hardware cause and effect for learning embedded systems

## AB360° with multicore Propeller

- Program in Blockly (visual) or C (text)
- Easy start yet simplifies building capable projects and real-world prototypes



## Shield-Bot with Arduino

- Program in C variant (text)
- Best for schools with Arduino-based tech programs

## cyber:bot with micro:bit (Propeller co-processor)

- Program in microPython (text)
- Best for schools focusing on Python to add a capable hardware dimension

# cyber:bot Expanded Team



[www.microbit.org](http://www.microbit.org)  
BBC Foundation Makes  
the Micro:bit



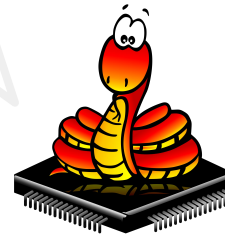
[www.parallax.com](http://www.parallax.com)  
cyber:bot Design and  
USA Manufacturing



<https://www.nicerc.org>  
Educator Training and  
Curricula



[www.codewith.mu](http://www.codewith.mu)  
Code Editor for  
Windows and Mac



[www.micropython.org](http://www.micropython.org)  
MicroPython Code Developer



# cyber:bot



# cyber:bot Goals

## ■ For educators:

- Be the class they remember!
- Turnkey system they can trust
- Scaffold capability
- Extend the use of micro:bit
- Support in-class competitions

## ■ For students:

- Inspire STEM careers
- Build/program one's own robot
- Learn Python language
- Build electronic circuits
- Learn troubleshooting

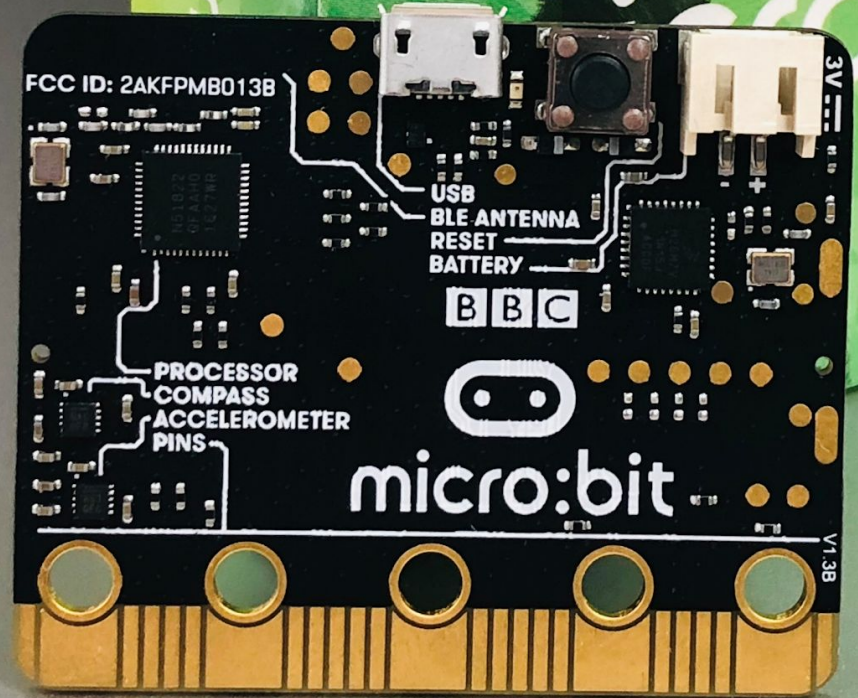
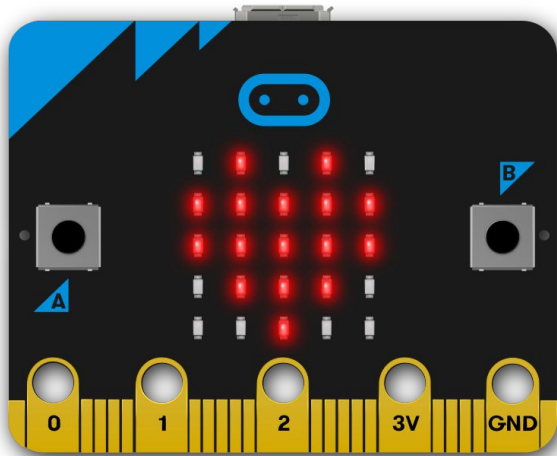
## ■ For Parallax / NICERC

- Sustainable business model
- Reinvest and add resources
- Professional Development



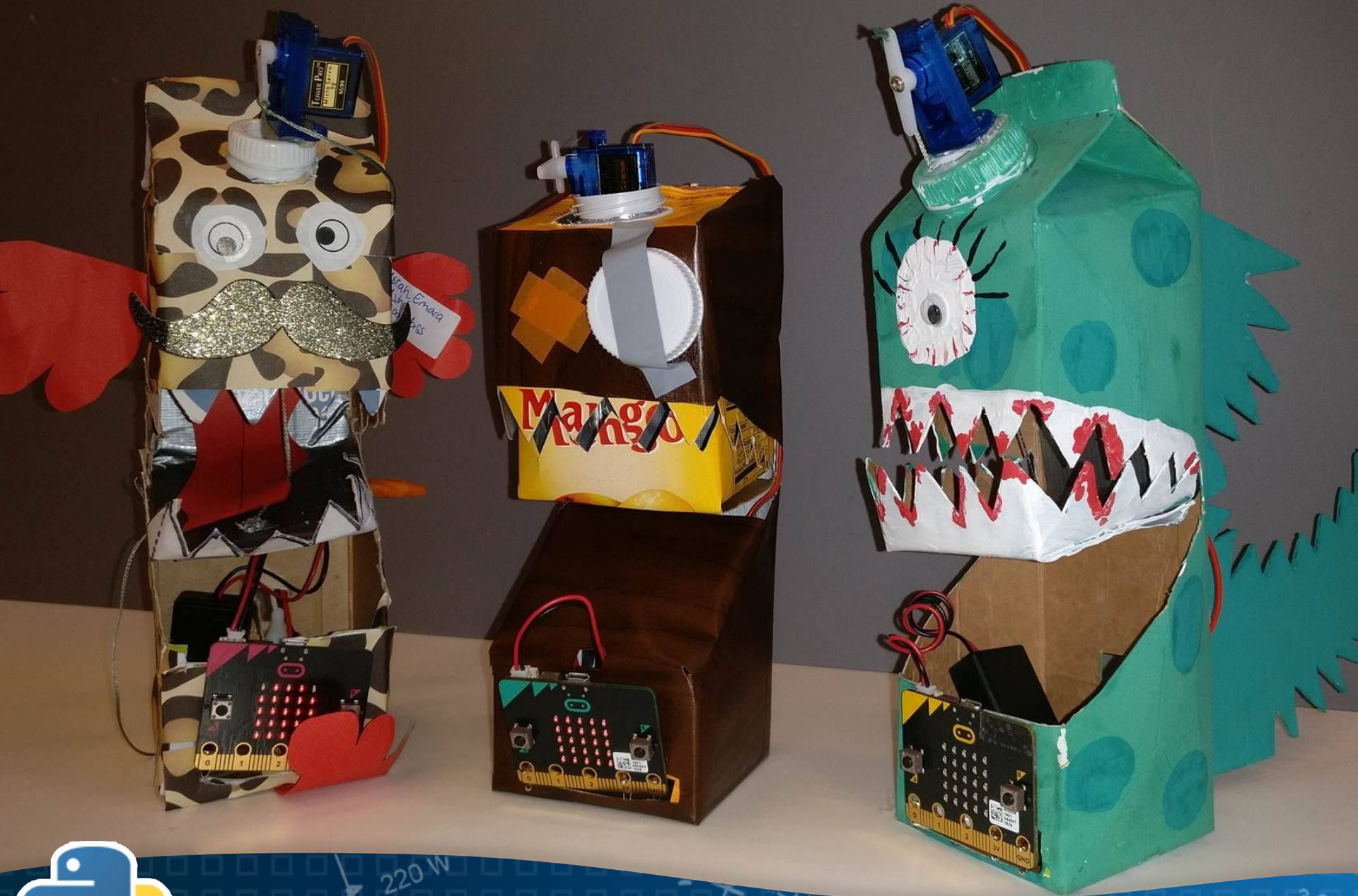


micro:bit

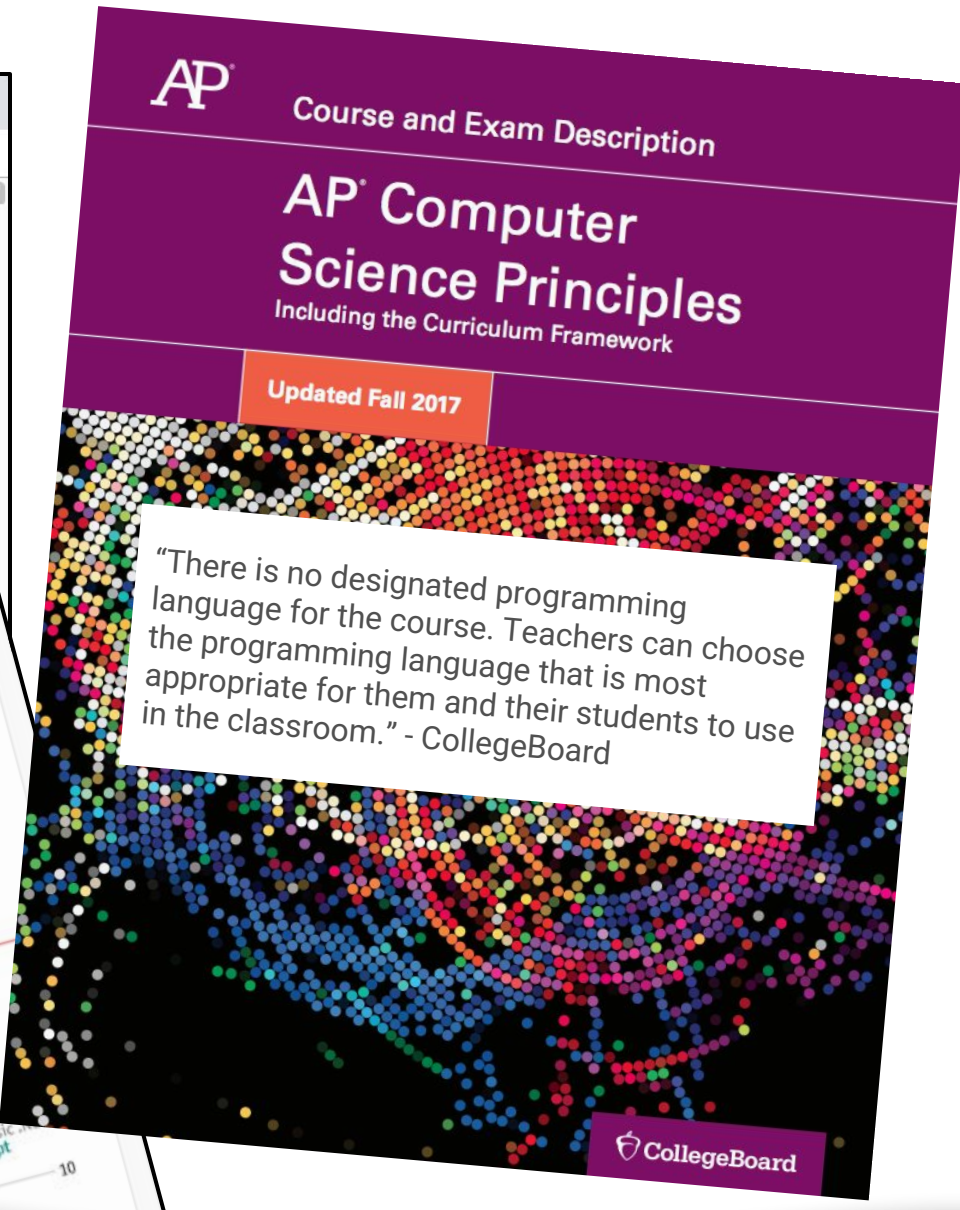
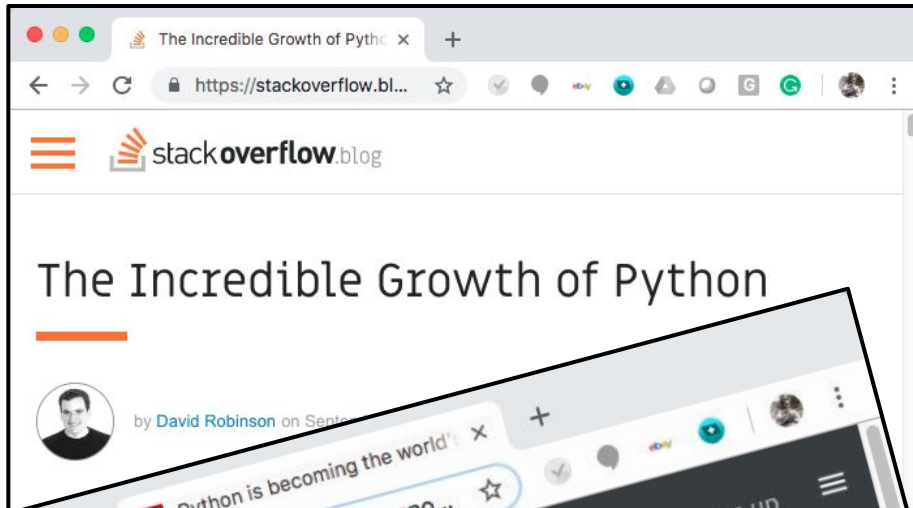


cyber:bot











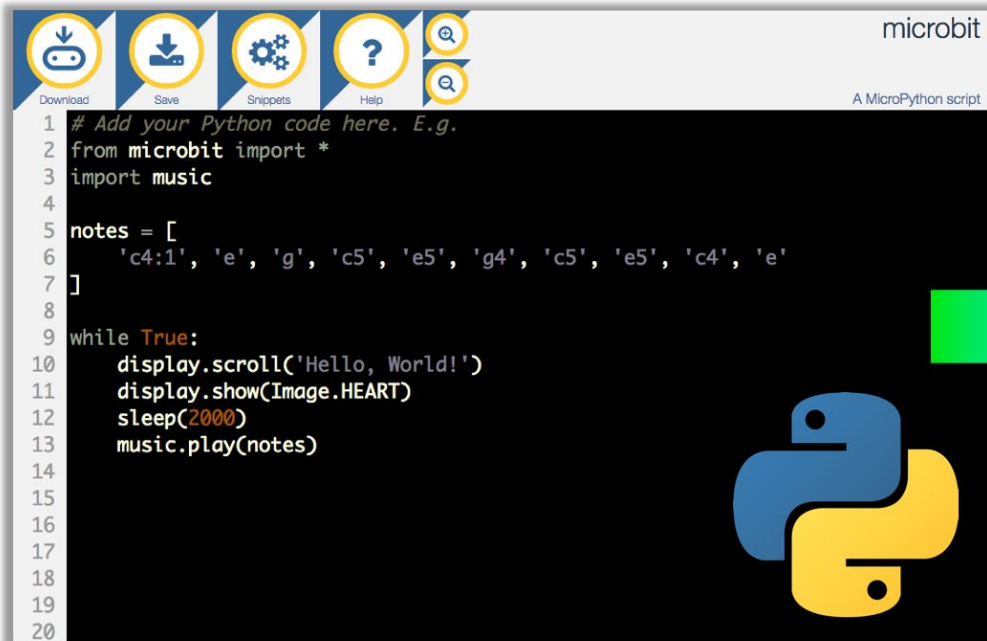
- Beginner-friendly (reads like English - looks BASIC)
- Object-oriented structured language
- Runs on embedded hardware (MicroPython)
- Programming tool support (open source, all OSs, etc.)
- Forces new programmers to use alignment/indentation for legibility (good practice)
- Not overly verbose - easier to "get at the heart" of the concept you're teaching (no wading through a bunch of meaningless syntax rules that obscure the instructional intent.)
- Free / open source (no awkward licensing/copyright)

○



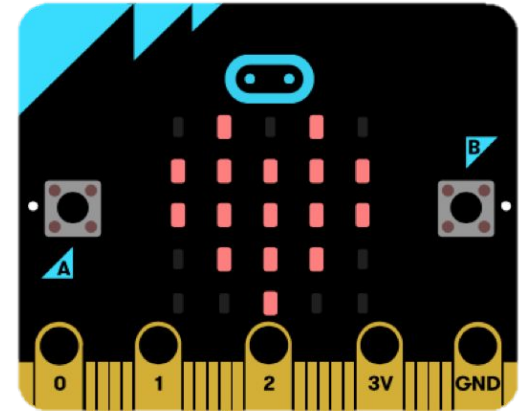



# MicroPython—Python for Microcontrollers

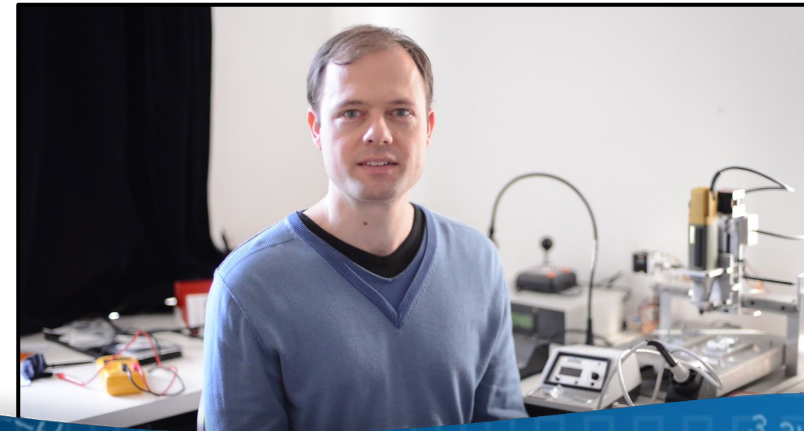


```
1 # Add your Python code here. E.g.
2 from microbit import *
3 import music
4
5 notes = [
6     'c4:1', 'e', 'g', 'c5', 'e5', 'g4', 'c5', 'e5', 'c4', 'e'
7 ]
8
9 while True:
10     display.scroll('Hello, World!')
11     display.show(Image.HEART)
12     sleep(2000)
13     music.play(notes)
14
15
16
17
18
19
20
```

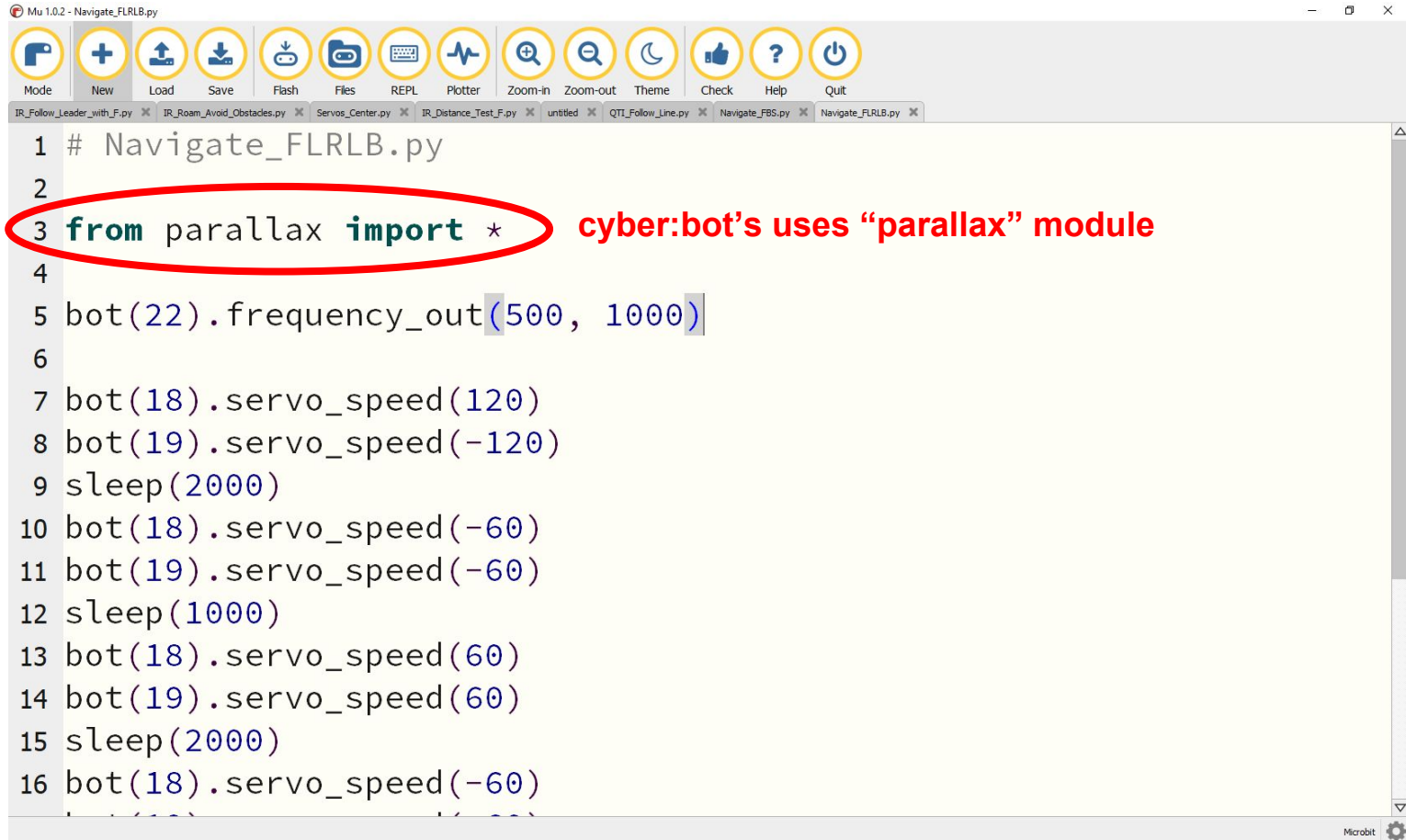
microbit  
A MicroPython script



MicroPython is a creation  
of Damien George



# Mu Editor with parallax.py Library



```
Mu 1.0.2 - Navigate_FLRLB.py
Mode New Load Save Flash Files REPL Plotter Zoom-in Zoom-out Theme Check Help Quit
IR_Follow_Leader_with_F.py IR_Room_Avoid_Obstacles.py Servos_Center.py IR_Distance_Test_F.py untitled QTI_Follow_Line.py Navigate_FBS.py Navigate_FLRLB.py
1 # Navigate_FLRLB.py
2
3 from parallax import * cyber:bot's uses "parallax" module
4
5 bot(22).frequency_out(500, 1000)
6
7 bot(18).servo_speed(120)
8 bot(19).servo_speed(-120)
9 sleep(2000)
10 bot(18).servo_speed(-60)
11 bot(19).servo_speed(-60)
12 sleep(1000)
13 bot(18).servo_speed(60)
14 bot(19).servo_speed(60)
15 sleep(2000)
16 bot(18).servo_speed(-60)
```





untitled 10

```
1 # Write your code here :-)
```

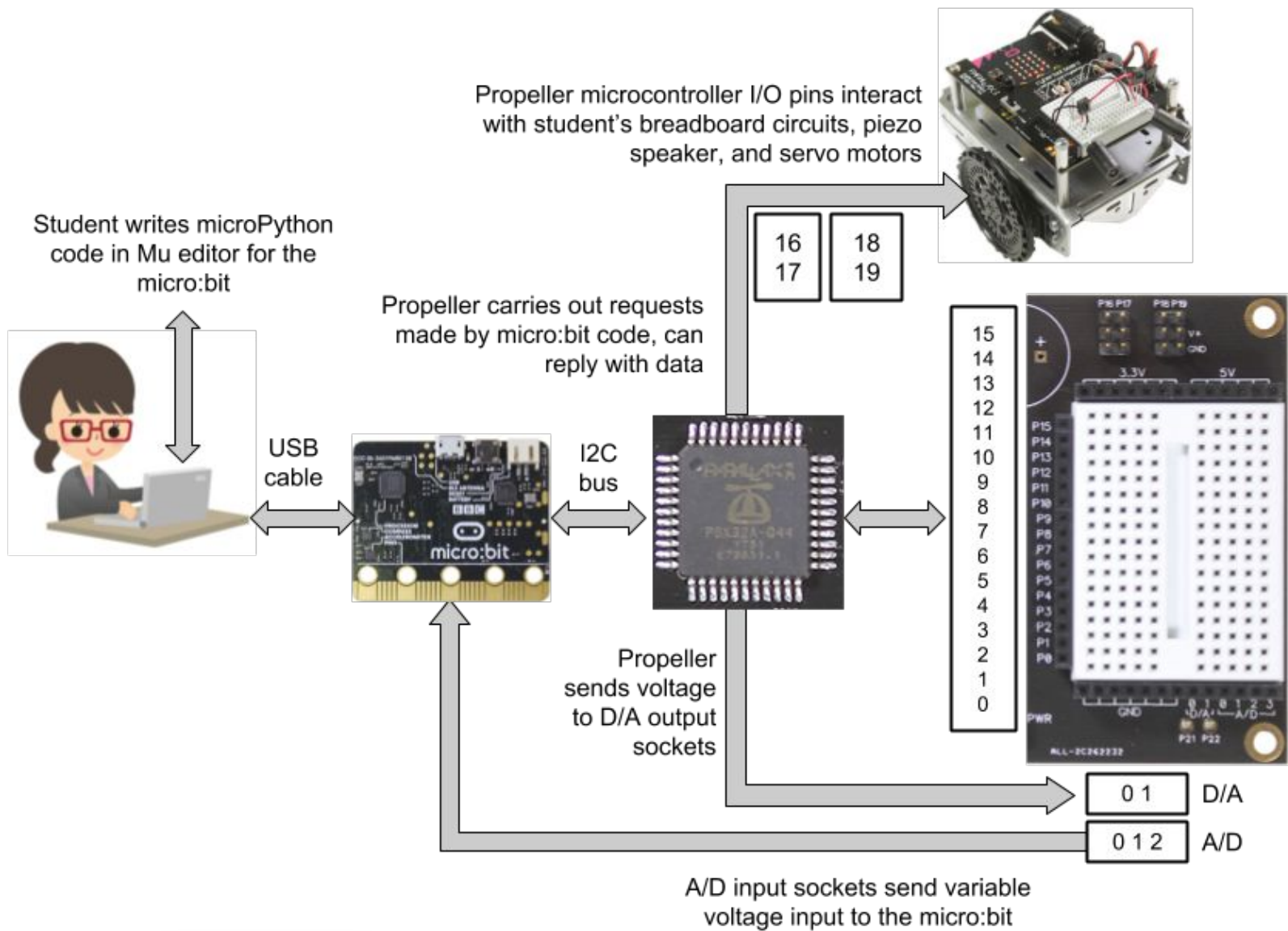
```
2
```



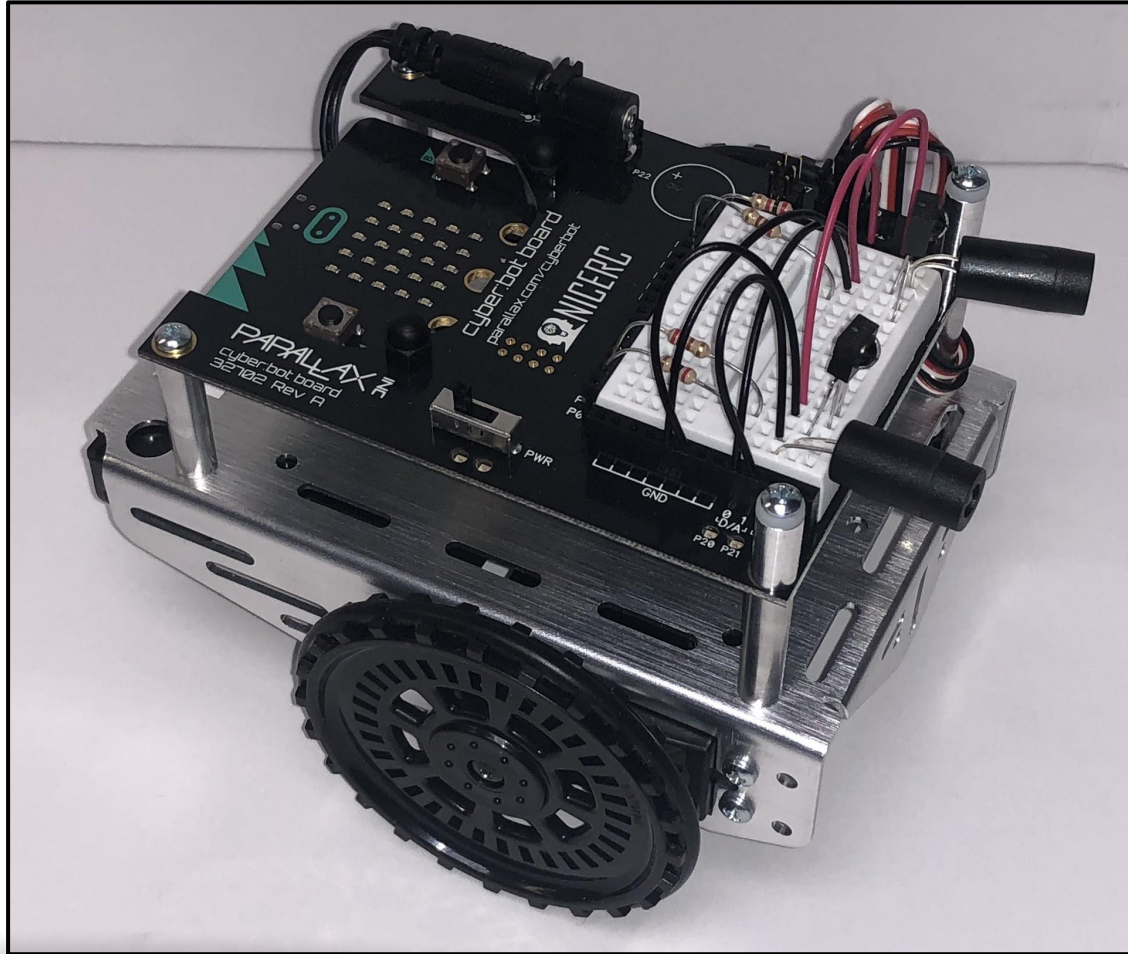
# parallax.py Library Module Methods

```
bot(pin).read_r(data)           # retrieve returned value via I2C
bot(pin).digital_write(state)   # set I/O pins high or low
bot(pin).analog_write(PWM)      # set duty cycle to four available PWM channels
bot(pin).digital_read(state)    # get I/O pin state high or low
bot(pin).states(states)        # set binary pin states to multiple I/Os
bot(pin).directions(directions) # set I/O pin directions
bot(pin).qti(QTI values)       # set and read four line follower sensors
bot(pin).pulse_out(pulsewidth)  # set and maintain a pulse
bot(pin).pulse_in(pulsewidth)   # measure pulse on I/O pin (accelerometers)
bot(pin).pulse_count(counts)    # count pulses over duration of time
bot(pin).rc_time(time)          # pseudo-analog R/C charge/discharge time on I/O pin
bot(pin).frequency_out(sound)   # set frequency, duration to I/O pin
bot(pin).ir_detect(frequency)   # generate IR pulse and get receiver value
bot(pin).servo_angle(angle)     # set and hold servo in an angle (up to 14 servos)
bot(pin).servo_speed(speed)     # set and hold servo speed (-100 to 100)
bot(pin).servo_disable(disable) # disable a servo
bot(pin).ping_distance(distance) # configure Ultrasonic or Laser Ping, receive distance
bot(pin).tv_remote(button)      # decode pulses from Sony TV remote and return button number
```





# cyber:bot (Top)



cyber:bot

220 W

Red

P8

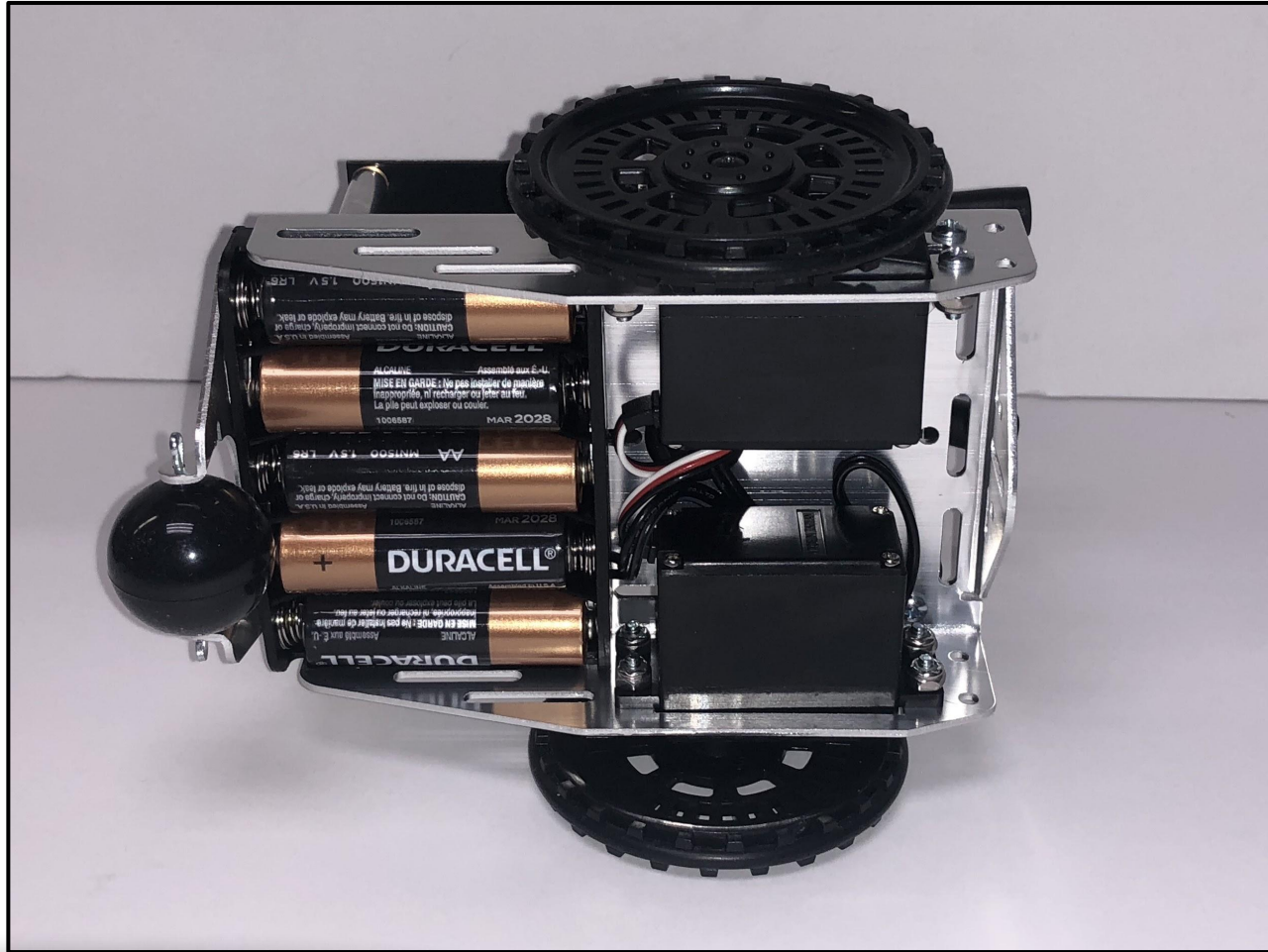
220 W

3.3V

GND



# cyber:bot (Bottom)



cyber:bot

220 W

Red

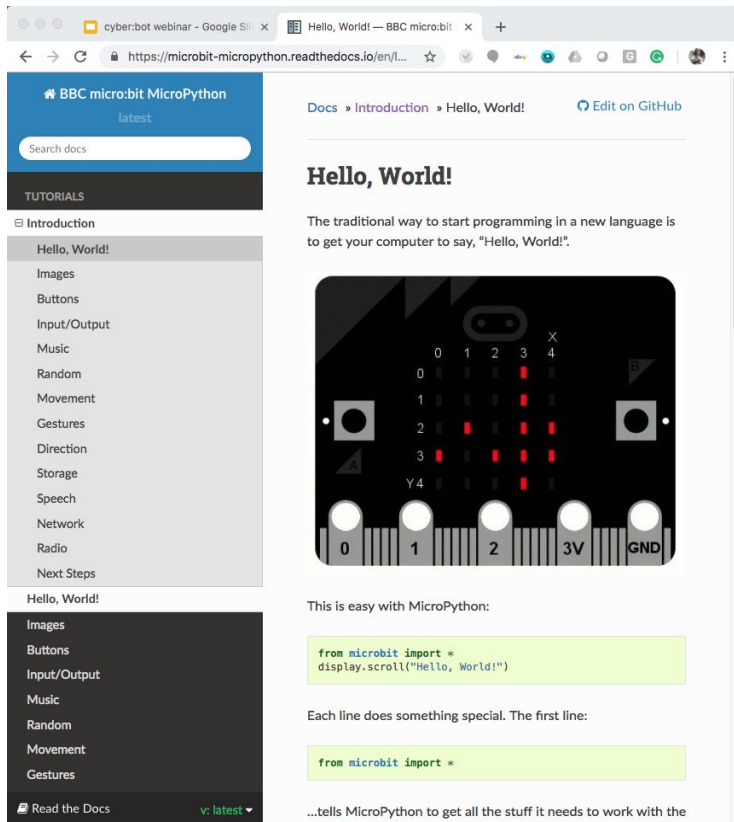
P8

220 W

3.3V

GND

# Key micro:bit Resources

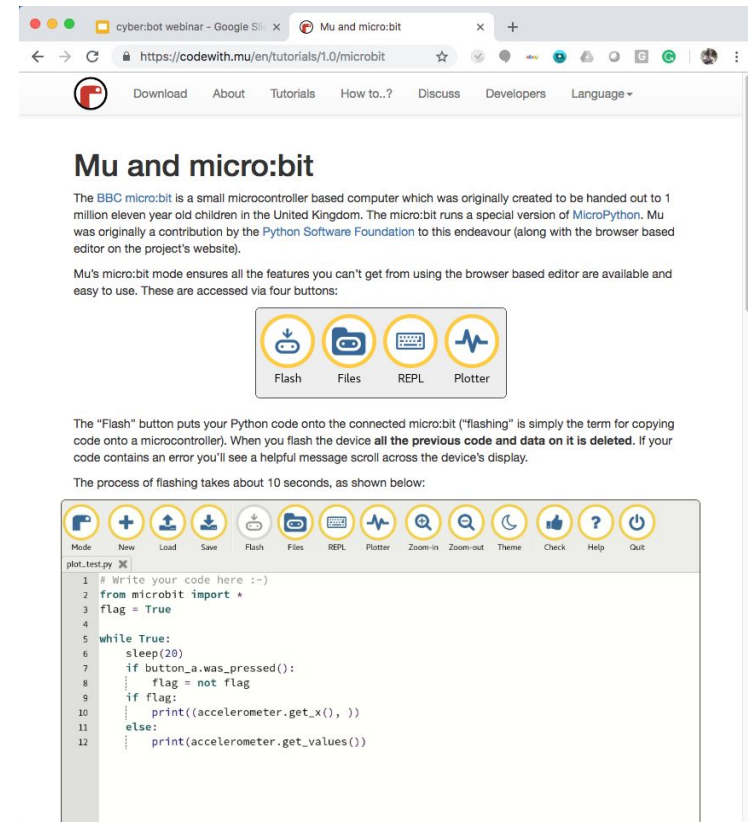


The screenshot shows the BBC micro:bit MicroPython website. The main heading is "Hello, World!". Below it, a paragraph explains that the traditional way to start programming is to get the computer to say "Hello, World!". A central image shows a micro:bit board with a grid of LEDs displaying the text "Hello, World!". Below the image, a code block shows the Python code: 

```
from microbit import *
display.scroll("Hello, World!")
```

 The text explains that each line does something special and that the first line tells MicroPython to get all the stuff it needs to work with the board.

<https://microbit.org>



The screenshot shows the Codewith.mu website. The main heading is "Mu and micro:bit". Below it, a paragraph explains that the BBC micro:bit is a small microcontroller based computer which was originally created to be handed out to 1 million eleven year old children in the United Kingdom. The micro:bit runs a special version of MicroPython. Mu was originally a contribution by the Python Software Foundation to this endeavour (along with the browser based editor on the project's website). A second paragraph states that Mu's micro:bit mode ensures all the features you can't get from using the browser based editor are available and easy to use. These are accessed via four buttons: Flash, Files, REPL, and Plotter. Below this, a screenshot of the Mu IDE interface shows a toolbar with icons for Mode, New, Load, Save, Flash, Files, REPL, Plotter, Zoom-in, Zoom-out, Theme, Check, Help, and Out. The main area displays a Python code snippet for a plotter test: 

```
1 # Write your code here :-))
2 from microbit import *
3 flag = True
4
5 while True:
6     sleep(20)
7     if button_a.was_pressed():
8         flag = not flag
9         if flag:
10            print((accelerometer.get_x(), ))
11        else:
12            print(accelerometer.get_values())
```

<https://codewith.mu>



# 12 micro:bit Tutorials from NICERC

[www.parallax.com/product/nicerc-cyber-curriculum](http://www.parallax.com/product/nicerc-cyber-curriculum)

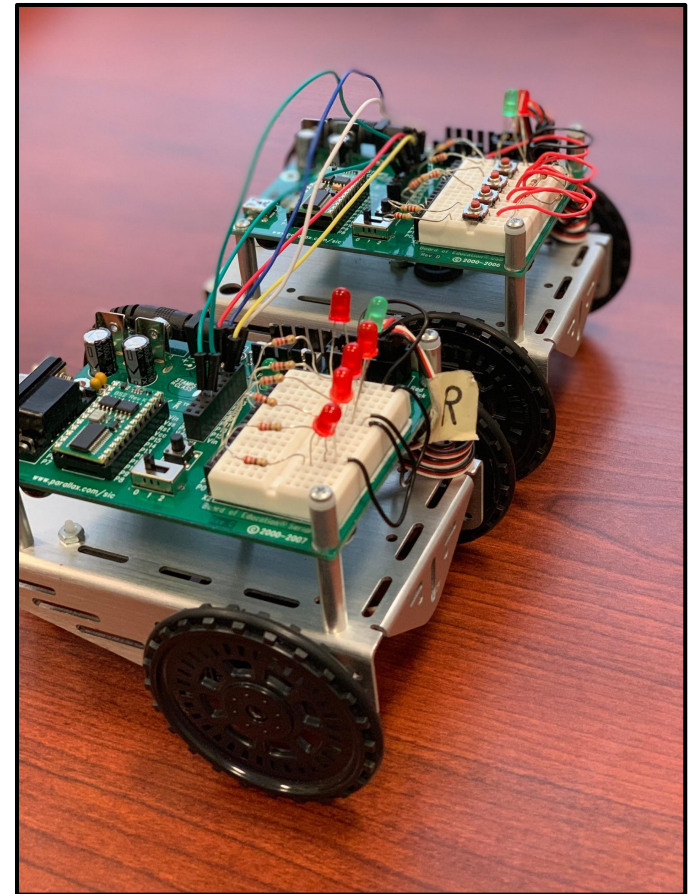
Lesson	Title
00	Graphics
01	Hello World and Scrolling Text
02	Programming with Displays
03	Variables and DIY Images
04	Animation
05	Buttons and Conditionals
06	Compass and Comparisons
07	Binary and Visual Counter
08	Tug-o-War
09	Communications
10	Student Response System
11	Passwords and Security
12	Voltage Measurement
13	Temperature Sensor





# Cybersecurity

- Cyber starts with understanding “how stuff works”
- Knowing how things work, you know how it *doesn't* work
- You know how adversaries might seek to break it
- Understanding a system helps harden that system



# cyber:bot Curriculum

- Tutorials available through [learn.parallax.com](http://learn.parallax.com)
- Free classroom curricula available for US school teachers through NICERC
  - Class-length units
  - Additional resources for teachers
  - Modular content
  - Workshops available for schools




**CYBER LITERACY**  
with Boe-Bot



Cyber Literacy with Boe-Bot® uses the Parallax Boe-Bot® platform to blend **robotics, programming, and electricity** with ethical elements of **cyber and humanities**.

- Electricity
- Robotics
- Programming
- Liberal Arts

[www.NICERC.org](http://www.NICERC.org)

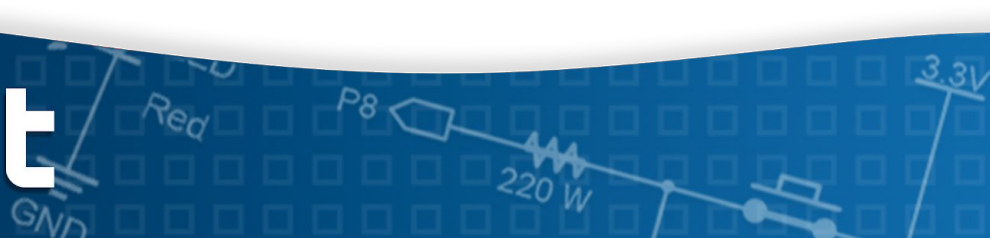
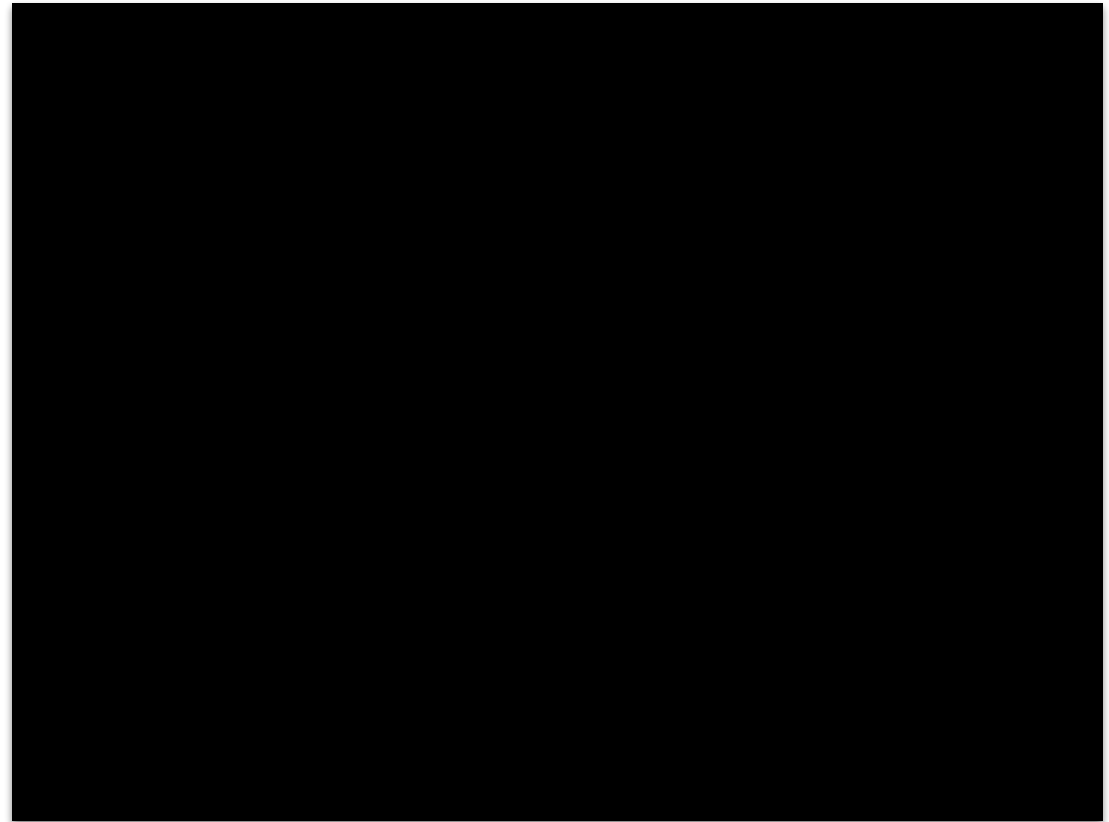


**NICERC**  
AN ACADEMIC DIVISION OF THE  
CYBER INNOVATION CENTER



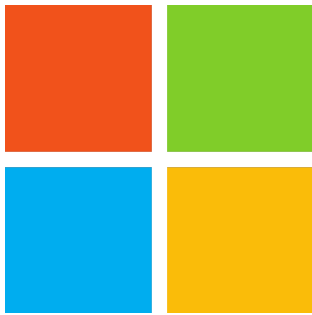
# Demonstrations

- Start off with a bang!
- Object Detection
  - Whiskers as a physical button-press sensor
  - Infrared for avoidance
  - Infrared for following
  - Ping))) Ultrasonic Sensor
  - Ping))) Laser Sensor
- Infrared Remote Control
- Light Following with Photoresistors
- Line Following





# Programming Operating System Compatibility



**Code with Mu**

<https://codewith.mu>

Download and install on your  
Windows computer.



**Code with Mu**

<https://codewith.mu>

Download and install on your Mac  
computer.



**micro:bit's online Python editor**

<https://python.microbit.org/v/1.1>

Copy the parallax.py library  
Paste to the top of your program

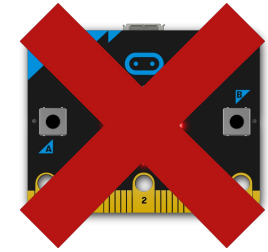
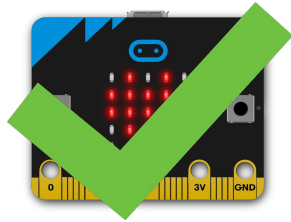


Me  
too!





# cyber:bot Available Formats



## cyber:bot Robot Kit w/ micro:bit

*Stock #32700*

\$200 ea. (qty 1-9)

\$190 ea. (qty 10-19)

\$180 ea. (qty 20+)

## cyber:bot Robot Kit NO micro:bit

*Stock #32705*

\$190 ea. (qty 1-9)

\$180 ea. (qty 10-19)

\$170 ea. (qty 20+)

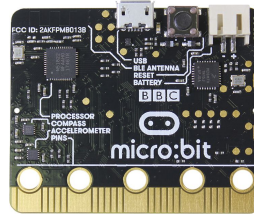
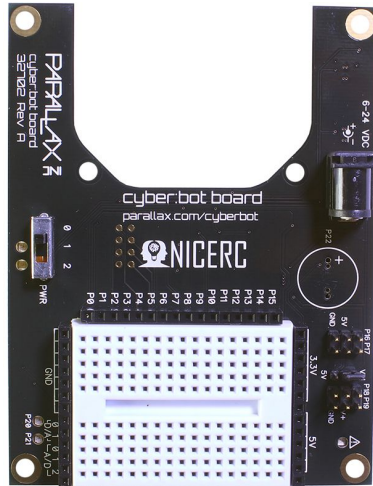




# cyber:bot conversion kit for Boe-Bot or Shield Bot with Arduino



or +



=



**cyber:bot conversion kit**

Stock #32707

\$79.99 ea. (qty 1-9)

\$76.00 ea. (qty 10-19)

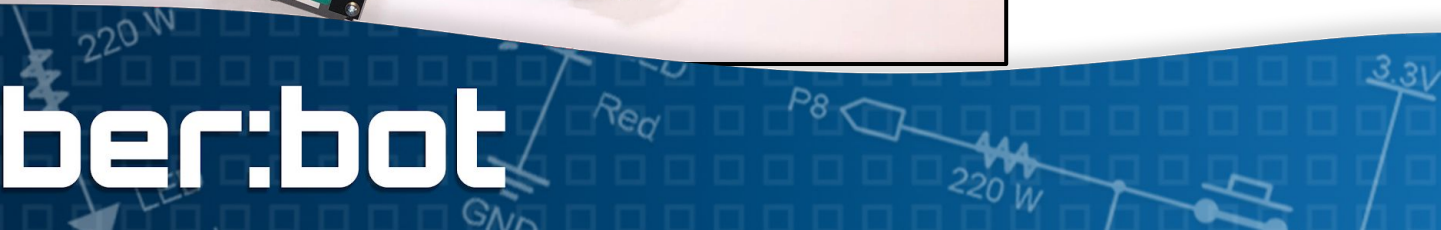


cyber:bot

# Roundtable Q&A



cyber:bot



# Parallax Educator Hotline



**Educator Hotline**  
**(916) 701-8625**



**cyber:bot**





A low-angle photograph of a blue building facade. The word "PARALLAX" is written in large, white, 3D block letters across the top. Below the letters is a modern architectural structure with white metal beams and glass panels. A circular light fixture is visible in the lower-left corner.

PARALLAX

thank you!

**Parallax Inc.**

599 Menlo Drive, Ste 100  
Rocklin, CA 95765

[www.parallax.com](http://www.parallax.com)

[Learn.parallax.com](http://Learn.parallax.com)

Main: (916) 624-8333

Educator Hotline: (916) 701-8625

A photograph of the National Integrated Cyber Education Research Center (NICERC) building at night. The building features several tall, illuminated, tapered columns that support a curved, cantilevered upper section. The interior lights of the building are visible through the glass panels. The sky is a deep blue, and the foreground is dark. The text "thank you!" is written in a white, cursive font in the upper right corner.

thank you!

**National Integrated Cyber Education  
Research Center, NICERC**  
6300 East Texas Street  
Bossier City, LA 71111

[www.nicerc.org](http://www.nicerc.org)  
Main: (318) 759-1600